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describe all possible classical mechanics problems The solution to a given mechanical problem is obtained by solving a set of N second-order differential equations known as Euler-Lagrange equations of motion, $\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} - \frac{\partial L}{\partial q_i} = 0$: (14) $\frac{\partial L}{\partial q_i}$ 3 CHAPTER 1 A REVIEW OF ANALYTICAL MECHANICS

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Lecture Notes on Classical Mechanics (A Work in Progress)

Lecture Notes on Classical Mechanics (A Work in Progress) Daniel Arovas Department of Physics University of California, San Diego May 8, 2013

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